

Relative velocity



A

B

if A is moving at  
velocity  $\vec{v}_A$  with respect  
to B  
(relative velocity)

if object has velocity  $\vec{v}_A$  in frame A  
has velocity  $\vec{v}_A + \vec{v}_B$  in frame B

still

$$2 \text{ mi/hr}$$

$$2 \text{ mi/hr}$$

$$1 \text{ mi}$$

Still water:

$$2 \text{ mi}$$

$$1^{\text{st}} \frac{1}{2} \text{ hr}$$

$$2^{\text{nd}} \frac{1}{2} \text{ hr}$$

$$1 \text{ hr} \Rightarrow 2 \text{ mi/hr}$$

current

$$\leftarrow 2+1 = 3 \text{ mi/hr}$$

$$\rightarrow 1 \text{ mi/hr}$$

$$\frac{1}{3} \text{ hr}$$

$$2-1 = 1 \text{ mi/hr}$$

$$\underline{1 \text{ hour}}$$

$$\frac{4}{3} \text{ hour}$$

$$\frac{2 \text{ mi}}{\frac{4}{3} \text{ hour}} = \frac{3}{2} \frac{\text{mi}}{\text{hr}}$$



## ch5 Newton's laws of motion

1) if an object has no forces acting on it,

its velocity is constant.

Force: that which causes an object to accelerate.

Force is a vector

## Units of force · Newtons.

for instance,  
can measure force by using  
a deformation of a spring

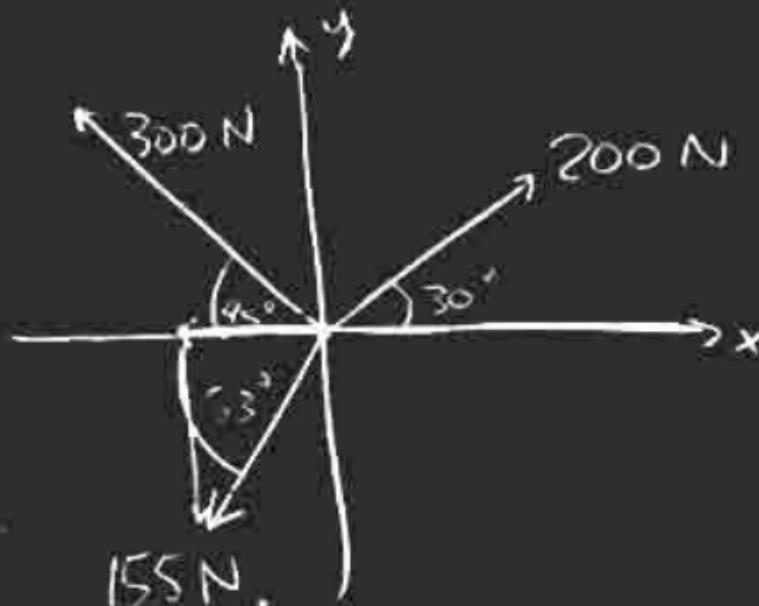


Force is a vector

$$\vec{F}_1 \downarrow + \vec{F}_2 \rightarrow = \vec{F}_1 + \vec{F}_2$$

$$\vec{F}_1 \uparrow + \vec{F}_2 \downarrow = 0$$

Add forces



Sig<sup>n</sup>s!

$ F $	$F_x$	$F_y$
200 N	$(200\text{N})\cos 30^\circ = 173\text{N}$	$(200\text{N})\sin 30^\circ = 100\text{N}$
300 N	$(300\text{N})\cos 45^\circ = -212\text{N}$	$(300\text{N})\sin 45^\circ = 212\text{N}$
155 N	$-(155\text{N})\cos 33^\circ = -132\text{N}$	$-(155\text{N})\sin 33^\circ = -124\text{N}$

$\times \quad F_x = -132\text{N} \quad F_y = 188\text{N}$

Magnitude of sum

$$\Rightarrow \sqrt{F_x^2 + F_y^2} = \sqrt{(-132)^2 + (188)^2} = 230\text{N}$$

$$\text{angle} > \tan^{-1}\left(\frac{-188}{132}\right) \approx -35^\circ$$

inclined plane problems



often useful to choose axes || and ⊥ to inclined plane

$$\vec{F}_g = -F_g \hat{j} = -F_g \cos\theta \hat{i} - F_g \sin\theta \hat{j}$$

$$\vec{N} = N \hat{i}$$

$$\vec{F}_f = F_f \hat{i}$$

total force

$$\vec{F} = (-F_g \sin\theta + F_f) \hat{i} + (-F_g \cos\theta + N) \hat{j}$$

if object is not accelerating  $\Rightarrow \vec{F} = 0$

$$F_g \sin\theta = F_f$$

$$F_g \cos\theta = N$$

Inertial reference frame:

a frame in which Newton's first law applies

Newton's Third Law

Force exerted by object 1 on object 2,  $\vec{F}_{12}$ , is equal in magnitude and opposite in direction to the force exerted by 2 on 1,  $\vec{F}_{21}$ .  $\vec{F}_{12} = -\vec{F}_{21}$

Newton's 2<sup>nd</sup> law

$$\sum \vec{F} = m\vec{a}$$

acceleration of body is proportional to NET force acting on + proportionality const. mass

mass. Scalar

units are kg.

$$\sum \vec{F} = m\vec{a}$$

is really saying

$F_x = m a_x$

$F_y = m a_y$

$F_z = m a_z$

---

m has units kg

a has units  $m/s^2$

Force has units  $(kg \cdot m)/s^2$

$1N = 1 \text{ kg} \cdot m/s^2$

mass measures inertia  
[ $\vec{F} = m\vec{a}$ ]

weight      force due to gravity =  $-mg$