

4/12/04

Vector Potential

Remember that $\vec{\nabla} \times \vec{E} \Rightarrow \vec{E} = -\vec{\nabla} V$ permits the introduction of scalar potential

Similarly $\vec{\nabla} \cdot \vec{B} \Rightarrow \vec{B} = \vec{\nabla} \times \vec{A}$
↑ vector potential

This form of $\vec{B} = \vec{\nabla} \times \vec{A}$ guarantees that $\vec{\nabla} \cdot \vec{B} = 0$

Note that \vec{A} is not unique (just like $V \rightarrow V + U$)

$$\vec{A}' \rightarrow \vec{A} + \vec{\nabla} \lambda$$

This leaves $\vec{\nabla} \times \vec{A}$ unchanged. This is called a gauge transformation

A particularly useful gauge condition:

$$\vec{\nabla} \cdot \vec{A} = 0 \quad \text{known as Coulomb gauge}$$

is usually chosen.

To prove this is always possible:

Suppose $\vec{\nabla} \cdot \vec{A} \neq 0$, let $\vec{A}' = \vec{A} + \nabla \lambda$

such that $\vec{\nabla} \cdot \vec{A}' = 0 \Rightarrow \nabla^2 \lambda = -\vec{\nabla} \cdot \vec{A}$

Poisson eqn with $f = \frac{\vec{\nabla} \cdot \vec{A}}{\epsilon_0}$

$$\text{Soln } \Rightarrow \lambda(\vec{r}) = \frac{1}{4\pi} \int \frac{\vec{\nabla}' \cdot \vec{A}' d\tau'}{|\vec{r} - \vec{r}'|}$$

In any case, we will therefore assume $\vec{\nabla} \cdot \vec{A} = 0$

The equation for \vec{A} is simplified in Coulomb gauge

$$\text{Ampere's law } \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

$$\Rightarrow \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \mu_0 \vec{J}$$

$$\Rightarrow \vec{\nabla} (\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A} = \mu_0 \vec{J}$$

$$\uparrow \text{analogue of } \vec{a} \times (\vec{b} \times \vec{c}) = \vec{b} (\vec{a} \cdot \vec{c}) - (\vec{a} \cdot \vec{b}) \vec{c}$$

$$\Rightarrow \nabla^2 \vec{A} = -\mu_0 \vec{J}$$

basically 3 Poisson eqn

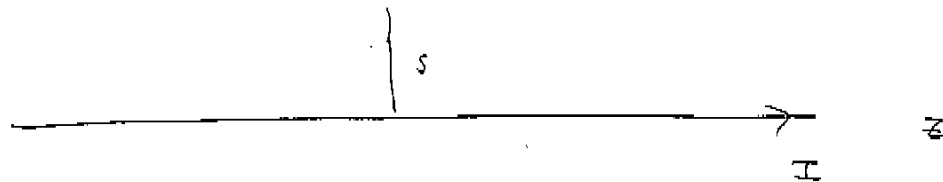
$$\Rightarrow \left\{ \begin{array}{l} \nabla^2 A_x = -\mu_0 J_x \\ \nabla^2 A_y = -\mu_0 J_y \\ \nabla^2 A_z = -\mu_0 J_z \end{array} \right.$$

We know the soln

$$\Rightarrow \vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}')}{|\vec{r} - \vec{r}'|} d\tau'$$

In a region where $\vec{J} = 0$, each component of \vec{A} satisfies the Laplace Eqn. \Rightarrow Machinery in C4.3

Again consider the simplest case



$$\vec{B} = \frac{\mu_0 I}{2\pi s} \hat{\phi}$$

$$B_\phi = \left(\frac{\partial A_s}{\partial z} - \frac{\partial A_z}{\partial s} \right)$$

For example:

~~$A_s = \frac{\mu_0 I z}{2\pi s}$~~
 ~~$A_z = -\frac{\mu_0 I}{4\pi} \ln s$~~ } can give B_ϕ

For Example $A_s = A_\phi = 0$

$$A_z = -\frac{\mu_0 I}{2\pi} \ln s \quad \text{will do}$$

$$\text{Check: } \vec{\nabla} \times \vec{A} = -\frac{\partial A_z}{\partial s} \hat{\phi} = \frac{\mu_0 I}{2\pi s} \hat{\phi} \quad \checkmark$$

$$\begin{aligned} \vec{\nabla} \cdot \vec{A} &= \frac{1}{s} \frac{\partial}{\partial s} (s A_s) + \frac{\partial A_z}{\partial z} + \frac{1}{s} \frac{\partial A_\phi}{\partial \phi} \\ &= 0 \quad \text{satisfies Coulomb gauge} \end{aligned}$$

Note that \vec{A} points in the same direction as the current. This is generally true.

If all current points in same direction

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}')}{|\vec{r} - \vec{r}'|} dz' \quad \text{suggest that } \vec{A} \parallel \vec{J}$$

But:

- ① We can add a constant vector to change direction of \vec{A} without affecting \vec{B}
- ② We can add even a more general $\lambda(\vec{r})$ (gauge transformations). Even without Coulomb gauge, we can choose any $\lambda(\vec{r})$ such that $\nabla^2 \lambda = 0$

⑤

Alternatively, $\nabla^2 A_z = 0$ outside wire

$$\Rightarrow A_z = c \ln s$$

(since the problem has symmetry in ϕ , we do not get $\sin n\phi$ or $\cos n\phi$ dependence)

Boundary condition

$$2\pi s (\vec{\nabla} \times \vec{A})_\phi = \mu_0 I$$

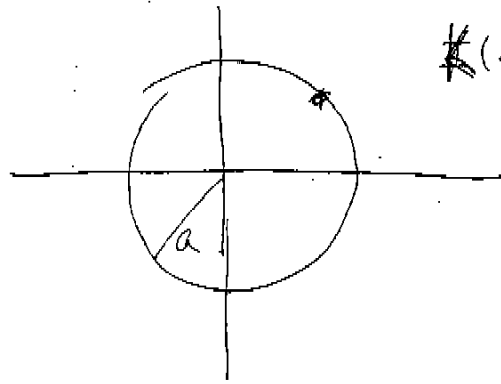
$$(\vec{\nabla} \times \vec{A})_\phi = \frac{\mu_0 I}{2\pi s}$$

But $(\vec{\nabla} \times \vec{A})_\phi = -\frac{c}{s}$

$$\Rightarrow c = -\frac{\mu_0 I}{2\pi}$$

$$\Rightarrow A_z = -\frac{\mu_0 I}{2\pi} \ln s$$

Example 2 =



$$f(\phi) = f_0 \cos \phi$$

Find \vec{A} & \vec{B}

Inside circle

$$(s < a)$$

$$\text{For } s < a \quad \nabla^2 A_z = 0$$

$$\Rightarrow A_z = C_1 \ln s + \sum_{n=1}^{\infty} (A_n s^n + B_n s^{-n}) (D_n \cos n\phi + E_n \sin n\phi)$$

For A_z to be well behaved at $s=0$

$$\Rightarrow C_1 = B_n = 0$$

$$\Rightarrow A_z = \sum_{n=1}^{\infty} A_n s^n (D_n \cos n\phi + E_n \sin n\phi)$$

Note that this form satisfies $\vec{\nabla} \cdot \vec{A} = \frac{\partial A_z}{\partial z} = 0$

since A_z is not a function of z

4/16/04

Ampere's law:

$$\oint B_{\phi} \cdot dl = \mu_0 I = \mu_0 K_0 \cos\phi \cdot a d\phi$$

$$2 B_{\phi} \cdot a d\phi = \mu_0 K_0 \cos\phi \cdot a d\phi$$

since B_{ϕ}
reverses
sign outside

$$B_{\phi} = - \frac{\mu_0 K_0 \cos\phi}{2}$$

Now $B_{\phi} = (\nabla \times \vec{A})_{\phi} = \left(\frac{\partial A_s}{\partial z} - \frac{\partial A_z}{\partial s} \right) = - \frac{\partial A_z}{\partial s}$

$$\Rightarrow - \frac{\mu_0 K_0 \cos\phi}{2} = - \sum_{n=1}^{\infty} n A_n s^{n-1} (D_n \cos n\phi + E_n \sin n\phi)$$

$$\Rightarrow \begin{aligned} E_n &= 0, \\ D_n &= 0 \quad \forall n \neq 1 \\ A_1 D_1 &= \frac{\mu_0 K_0}{2} \end{aligned}$$

$$\Rightarrow A_z = \frac{\mu_0 K_0}{2} s \cos\phi = \frac{\mu_0 K_0}{2} x$$

$$\Rightarrow \vec{B} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & \frac{\mu_0 K_0 x}{2} \end{vmatrix} = - \frac{\mu_0 K_0}{2} \hat{y}$$

uniform

1)

→ Example 3: Long Solenoid $B_z = \mu_0 n I$ inside

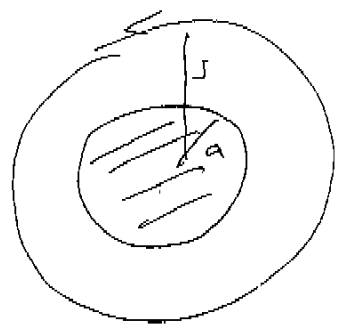
$$\oint \vec{A} \cdot d\vec{l} = \int \vec{B} \cdot d\vec{a} = (\mu_0 n I)(\pi s^2)$$

$$A\phi = \frac{\mu_0 n I s}{2} \quad s < a$$

Outside the solenoid, $B_z = 0$

but $(2\pi s) A\phi = \pi a^2 \cdot \mu_0 n I$

$$A\phi = \frac{\mu_0 n I a^2}{2s} \quad s > a$$



Therefore $A\phi \neq 0$ even though

$$B_z = (\vec{\nabla} \times \vec{A})_z = \frac{1}{s} \frac{\partial}{\partial s} (s A\phi) = 0$$

The Lagrangian / Hamiltonian formalism of Mechanics involves the potential \vec{A}, V rather than the fields \vec{E}, \vec{B}

$$H = \frac{p^2}{2m} + eV \rightarrow \frac{1}{2m} (\vec{p} - e\vec{A})^2 + eV$$

Aharonov - Bohm effect.

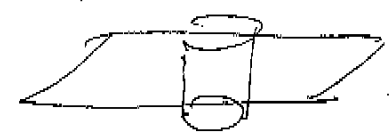
Boundary Conditions for \vec{B}

Recall that we are solving $\nabla^2 \vec{A} = -\mu_0 \vec{J}$

(analogous to $\nabla^2 V = -\rho/\epsilon_0$)

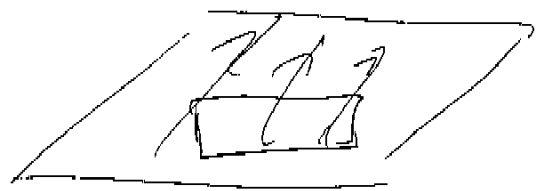
Soln is subject to b.c. (cf. E-field)

• $\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow$ $B_{\text{above}}^\perp = \cancel{B_{\text{above}}^\perp} B_{\text{below}}^\perp$



• $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \Rightarrow \oint \vec{B} \cdot d\vec{l} = \mu_0 I$

$\Rightarrow B_{\text{above}}'' - B_{\text{below}}'' = \mu_0 K$

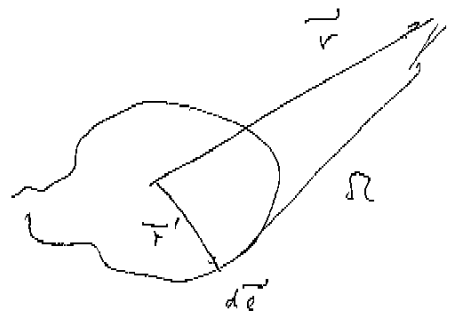


\Rightarrow $B_{\text{above}}'' - B_{\text{below}}'' = \mu_0 K$

• \vec{A} is continuous $\vec{A}_{\text{above}} = \vec{A}_{\text{below}}$

Multiple Expansion

$$\begin{aligned}\vec{A}(\vec{r}) &= \frac{\mu_0 I}{4\pi} \oint \frac{d\vec{r}'}{\Omega} \\ &= \frac{\mu_0 I}{4\pi} \oint \frac{d\vec{e}'}{|\vec{r} - \vec{r}'|}\end{aligned}$$



Consider $r > r'$

$$\frac{1}{|\vec{r} - \vec{r}'|} = \frac{1}{(r^2 + r'^2 - 2rr'\cos\Omega)^{1/2}} = \frac{1}{r} \sum_{l=0}^{\infty} \left(\frac{r'}{r}\right)^l P_l(\cos\Omega)$$

$$\begin{aligned}\text{So } \vec{A}(\vec{r}) &= \frac{\mu_0 I}{4\pi r} \oint \sum_{l=0}^{\infty} \left(\frac{r'}{r}\right)^l P_l(\cos\Omega) d\vec{e}' \\ &= \frac{\mu_0 I}{4\pi r} \left\{ \oint d\vec{e}' + \frac{1}{r} \oint r' \cos\Omega d\vec{e}' \right. \\ &\quad \left. + \frac{1}{r^2} \oint r'^2 P_2(\cos\Omega) d\vec{e}' \right. \\ &\quad \left. + \dots \right\}\end{aligned}$$

Obviously $\oint d\vec{e}' = 0 \Rightarrow$ no monopole term
(remember the starting pt of $\vec{B} = \vec{\nabla} \times \vec{A}$ is $\vec{\nabla} \cdot \vec{B} = 0$)

The leading term is the dipole term

$$\vec{A}_{\text{dipole}}(\vec{r}) = \frac{\mu_0 I}{4\pi r^2} \oint r' \cos \theta' d\vec{l}'$$

$$= \frac{\mu_0 I}{4\pi r^2} \oint \vec{r}' \cdot \hat{r} d\vec{l}'$$

We can show that

$$\oint (\hat{r} \cdot \vec{r}') d\vec{l}' = -\hat{r} \times \int d\vec{a}' \quad [\text{Ch 1}]$$

FF Aside: This follows from a variation of Stokes's thm. Let $\vec{v} = \vec{c}T$ in Stokes's thm

$$\int_S (\vec{v}T) \times d\vec{a} = - \oint T d\vec{l} \quad \vec{c} = \text{constant vector.}$$

Now Let $\vec{T} = \vec{c} \cdot \vec{r}$ where $\vec{c} = \text{constant}$

$$\oint (\vec{c} \cdot \vec{r}) d\vec{l} = \vec{a} \times \vec{c} \quad \text{where}$$

$$\vec{a} = \frac{1}{2} \oint \vec{r} \times d\vec{l}$$

Therefore $\vec{A}_{\text{dipole}}(\vec{r}) = \frac{\mu_0 I}{4\pi r^2} \left(\int d\vec{a} \right) \times \hat{r}$

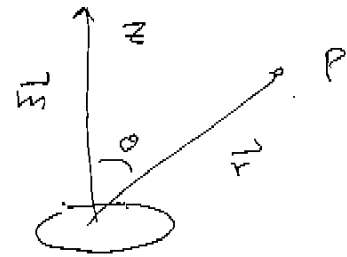
Define the magnetic dipole moment $\vec{m} = I \int d\vec{a} = I \vec{a}$

and $\vec{A}_{\text{dipole}}(\vec{r}) = \frac{\mu_0 I}{4\pi r^2} (\vec{m} \times \hat{r})$

Compare to $V_{\text{dipole}} = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \hat{r}}{r^2}$ $\vec{p} \leftrightarrow \vec{m}$
dot \leftrightarrow cross

Let \vec{m} be along z

then $\vec{m} \times \vec{r} = m \sin\theta \hat{\phi}$



$\vec{A}_{\text{dipole}}(\vec{r}) = \frac{\mu_0}{4\pi r^2} m \sin\theta \hat{\phi}$

$\vec{B} = \nabla \times \vec{A} = \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} \sin\theta A_{\phi} \hat{r} - \frac{1}{r} \frac{\partial}{\partial r} (r A_{\phi}) \hat{\theta}$

$= \frac{\mu_0 m}{4\pi} \left[\frac{\hat{r}}{r \sin\theta} \frac{\partial}{\partial \theta} \left(\frac{\sin^2\theta}{r^2} \right) - \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\sin\theta}{r^2} \right) \right] \hat{\theta}$

$= \frac{\mu_0 m}{4\pi} \left(\frac{2 \cos\theta}{r^3} \hat{r} + \frac{\sin\theta}{r^3} \hat{\theta} \right)$

$= \frac{\mu_0 m}{4\pi r^3} (2 \cos\theta \hat{r} + \sin\theta \hat{\theta})$ (Eq. 5.86)

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More compactly, $\vec{m} = m \hat{z} = m(\cos\theta \hat{r} - \sin\theta \hat{\theta})$

$$\vec{B}_{\text{dipole}}(\vec{r}) = \frac{\mu_0}{4\pi} \frac{1}{r^3} \left[3(\vec{m} \cdot \hat{r}) \hat{r} - \vec{m} \right]$$

Eq. 5.87

Compare

$$\vec{E}_{\text{dipole}}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} \left[3(\vec{p} \cdot \hat{r}) \hat{r} - \vec{p} \right]$$

Eq. 3.104

They have the same form!