

58) (a) $L_z = \frac{\hbar}{i} (x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x})$ where we will need to

write $\frac{\partial \psi}{\partial x} = \frac{\partial \psi}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial \psi}{\partial \theta} \frac{\partial \theta}{\partial x} + \frac{\partial \psi}{\partial \phi} \frac{\partial \phi}{\partial x}$ etc

So we need $\frac{\partial r}{\partial x} = \frac{\partial}{\partial x} [x^2 + y^2 + z^2]^{\frac{1}{2}} = \frac{1}{2} (2x) (x^2 + y^2 + z^2)^{-\frac{1}{2}} = \frac{x}{r}$

Similarly $\frac{\partial r}{\partial y} = \frac{y}{r}$

Next $\frac{\partial \theta}{\partial x} = \frac{\partial}{\partial x} \tan^{-1} \left[\frac{z}{\sqrt{x^2 + y^2}} \right] = \frac{1}{1 + z^2/(x^2 + y^2)} (z) \left(-\frac{1}{2}\right) (x^2 + y^2)^{-\frac{3}{2}} (2x)$
 $= \frac{x^2 + y^2}{x^2 + y^2 + z^2} (-) \frac{zx}{(x^2 + y^2)^{3/2}} = - \frac{xz}{r^2} \frac{1}{\sqrt{x^2 + y^2}}$

Similarly $\frac{\partial \theta}{\partial y} = - \frac{yz}{r^2} \frac{1}{\sqrt{x^2 + y^2}}$

Finally $\frac{\partial \phi}{\partial x} = \frac{\partial}{\partial x} \tan^{-1} \frac{y}{x} = \frac{1}{1 + (y/x)^2} \left(-\frac{y}{x^2}\right) = -\frac{y}{x^2 + y^2}$

$\frac{\partial \phi}{\partial y} = \frac{\partial}{\partial y} \tan^{-1} \frac{y}{x} = \frac{1}{1 + (y/x)^2} \left(\frac{1}{x}\right) = +\frac{x}{x^2 + y^2}$

$L_z \psi = \frac{\hbar}{i} \left\{ \left[x \frac{\partial \psi}{\partial y} \frac{\partial \psi}{\partial r} - y \frac{\partial \psi}{\partial x} \frac{\partial \psi}{\partial r} \right] + \left[x \frac{\partial \psi}{\partial y} \frac{\partial \psi}{\partial \theta} - y \frac{\partial \psi}{\partial x} \frac{\partial \psi}{\partial \theta} \right] + \left[x \frac{\partial \psi}{\partial y} \frac{\partial \psi}{\partial \phi} - y \frac{\partial \psi}{\partial x} \frac{\partial \psi}{\partial \phi} \right] \right\}$

$= \frac{\hbar}{i} \left\{ \left[x \cdot \frac{y}{r} - y \frac{x}{r} \right] \frac{\partial \psi}{\partial r} + \left[x \left(-\frac{yz}{r^2} \frac{1}{\sqrt{x^2 + y^2}}\right) - y \left(-\frac{xz}{r^2} \frac{1}{\sqrt{x^2 + y^2}}\right) \right] \frac{\partial \psi}{\partial \theta} + \left[x \left(\frac{x}{x^2 + y^2}\right) - y \left(\frac{-y}{x^2 + y^2}\right) \right] \frac{\partial \psi}{\partial \phi} \right\}$

$= \frac{\hbar}{i} \left\{ 0 \frac{\partial \psi}{\partial r} + 0 \frac{\partial \psi}{\partial \theta} + 1 \frac{\partial \psi}{\partial \phi} \right\} = \frac{\hbar}{i} \frac{\partial \psi}{\partial \phi} \Rightarrow \boxed{L_z = \frac{\hbar}{i} \frac{\partial}{\partial \phi}}$

$$(b) \quad L_x = + \frac{\hbar}{i} \left[-\sin\varphi \frac{\partial}{\partial\theta} - \cot\theta \cos\varphi \frac{\partial}{\partial\varphi} \right]$$

$$x = r \sin\theta \cos\varphi \quad y = r \sin\theta \sin\varphi \quad z = r \cos\theta$$

$$\frac{\partial\psi}{\partial\theta} = \frac{\partial\psi}{\partial x} \frac{\partial x}{\partial\theta} + \frac{\partial\psi}{\partial y} \frac{\partial y}{\partial\theta} + \frac{\partial\psi}{\partial z} \frac{\partial z}{\partial\theta}$$

$$= r \cos\theta \cos\varphi \frac{\partial\psi}{\partial x} + r \cos\theta \sin\varphi \frac{\partial\psi}{\partial y} - r \sin\theta \frac{\partial\psi}{\partial z}$$

$$\frac{\partial\psi}{\partial\varphi} = \frac{\partial\psi}{\partial x} \frac{\partial x}{\partial\varphi} + \frac{\partial\psi}{\partial y} \frac{\partial y}{\partial\varphi} + \frac{\partial\psi}{\partial z} \frac{\partial z}{\partial\varphi}$$

$$= -r \sin\theta \sin\varphi \frac{\partial\psi}{\partial x} + r \sin\theta \cos\varphi \frac{\partial\psi}{\partial y} + 0$$

$$L_x = \frac{\hbar}{i} \left\{ -\sin\varphi \left(r \cos\theta \cos\varphi \frac{\partial\psi}{\partial x} + r \cos\theta \sin\varphi \frac{\partial\psi}{\partial y} - r \sin\theta \frac{\partial\psi}{\partial z} \right) \right.$$

$$\left. - \frac{\cos\varphi}{\sin\theta} \cos\varphi \left(-r \sin\theta \sin\varphi \frac{\partial\psi}{\partial x} + r \sin\theta \cos\varphi \frac{\partial\psi}{\partial y} \right) \right\}$$

$$= \frac{\hbar}{i} \left\{ -r \cos\theta (\sin^2\varphi + \cos^2\varphi) \frac{\partial\psi}{\partial y} + r \sin\theta \sin\varphi \frac{\partial\psi}{\partial z} \right\}$$

$$= \frac{\hbar}{i} \left\{ -z \frac{\partial\psi}{\partial y} + y \frac{\partial\psi}{\partial z} \right\} \Rightarrow \boxed{L_x = \frac{\hbar}{i} \left[y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right]}$$

59) Lets begin with L_x^2 . From 58

$$L_x L_x \psi = -\hbar^2 \left[-\sin\varphi \frac{\partial}{\partial\theta} - \cot\theta \cos\varphi \frac{\partial}{\partial\varphi} \right] \left[-\sin\varphi \frac{\partial}{\partial\theta} - \cot\theta \cos\varphi \frac{\partial}{\partial\varphi} \right] \psi$$

$$= -\hbar^2 \left\{ \sin\varphi \frac{\partial}{\partial\theta} \sin\varphi \frac{\partial\psi}{\partial\theta} + \sin\varphi \frac{\partial}{\partial\theta} \cot\theta \cos\varphi \frac{\partial\psi}{\partial\varphi} \right.$$

$$\left. + \cot\theta \cos\varphi \frac{\partial}{\partial\theta} \sin\varphi \frac{\partial\psi}{\partial\theta} + \cot\theta \cos\varphi \frac{\partial}{\partial\theta} \cot\theta \cos\varphi \frac{\partial\psi}{\partial\varphi} \right\}$$

$$\begin{aligned}\frac{\partial}{\partial \theta} \cot \theta &= \frac{\partial}{\partial \theta} \frac{\cos \theta}{\sin \theta} = -\frac{\sin \theta}{\sin^2 \theta} - \frac{\cos \theta}{\sin^2 \theta} \cdot \cos \theta = -\frac{\sin^2 \theta + \cos^2 \theta}{\sin^2 \theta} \\ &= -\frac{1}{\sin^2 \theta}.\end{aligned}$$

So

$$\begin{aligned}L_x^2 \psi &= -\hbar^2 \left\{ \sin^2 \theta \frac{\partial^2 \psi}{\partial \theta^2} + \sin \theta \cos \theta \left[-\frac{1}{\sin^2 \theta} \frac{\partial \psi}{\partial \theta} + \cot \theta \frac{\partial^2 \psi}{\partial \theta \partial \phi} \right] \right. \\ &\quad \left. + \cot \theta \cos \theta \left[\cos \theta \frac{\partial \psi}{\partial \theta} + \sin \theta \frac{\partial^2 \psi}{\partial \theta \partial \phi} \right] \right. \\ &\quad \left. + \cot^2 \theta \cos \theta \left[-\sin \theta \frac{\partial \psi}{\partial \theta} + \cos \theta \frac{\partial^2 \psi}{\partial \theta^2} \right] \right\}\end{aligned}$$

The result for $L_y^2 \psi$ is similar except for some $\cos \theta \leftrightarrow \sin \theta$ interchanges and sign changes. I get

$$\begin{aligned}L_y^2 \psi &= -\hbar^2 \left\{ \cos^2 \theta \frac{\partial^2 \psi}{\partial \theta^2} - \sin \theta \cos \theta \left[-\frac{1}{\sin^2 \theta} \frac{\partial \psi}{\partial \theta} + \cot \theta \frac{\partial^2 \psi}{\partial \theta \partial \phi} \right] \right. \\ &\quad \left. - \cot \theta \sin \theta \left[-\sin \theta \frac{\partial \psi}{\partial \theta} + \cos \theta \frac{\partial^2 \psi}{\partial \theta \partial \phi} \right] \right. \\ &\quad \left. + \cot^2 \theta \sin \theta \left[\cos \theta \frac{\partial \psi}{\partial \theta} + \sin \theta \frac{\partial^2 \psi}{\partial \theta \partial \phi} \right] \right\}.\end{aligned}$$

When we combine the two parts, many terms cancel and we have

$$\begin{aligned}(L_x^2 + L_y^2) \psi &= -\hbar^2 \left\{ (\sin^2 \theta + \cos^2 \theta) \frac{\partial^2 \psi}{\partial \theta^2} + \cot \theta (\cos^2 \theta + \sin^2 \theta) \frac{\partial \psi}{\partial \theta} \right. \\ &\quad \left. + \cot^2 \theta (\cos^2 \theta + \sin^2 \theta) \frac{\partial^2 \psi}{\partial \theta^2} \right\} \\ &= -\hbar^2 \left\{ \frac{\partial^2 \psi}{\partial \theta^2} + \cot \theta \frac{\partial \psi}{\partial \theta} + \cot^2 \theta \frac{\partial^2 \psi}{\partial \theta^2} \right\}\end{aligned}$$

$$L_z^2 \psi = -\hbar^2 \frac{\partial^2 \psi}{\partial \theta^2} \Rightarrow$$

$$L^2 \psi = -\hbar^2 \left\{ \frac{\partial^2 \psi}{\partial \theta^2} + \cot \theta \frac{\partial \psi}{\partial \theta} + \left(\frac{\cos^2 \theta}{\sin^2 \theta} + 1 \right) \frac{\partial^2 \psi}{\partial \theta^2} \right\}$$

$$L^2 = -\hbar^2 \left\{ \frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right\}$$

Notice that

$$\begin{aligned} \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial \psi}{\partial \theta} &= \frac{1}{\sin \theta} \left[\cos \theta \frac{\partial \psi}{\partial \theta} + \sin \theta \frac{\partial^2 \psi}{\partial \theta^2} \right] \\ &= \cot \theta \frac{\partial \psi}{\partial \theta} + \frac{\partial^2 \psi}{\partial \theta^2} \end{aligned}$$

so our L^2 can be written in "standard" form

$$L^2 = -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right]$$

(b) (a) We have eigenfunctions of L_z which look like this

$$Y_1^1 = -\sqrt{\frac{3}{8\pi}} \frac{x+iy}{r}; \quad Y_1^0 = \sqrt{\frac{3}{4\pi}} \frac{z}{r}; \quad Y_1^{-1} = \sqrt{\frac{3}{8\pi}} \frac{x-iy}{r}$$

Since

$L_z = x p_y - y p_x$ and $L_x = y p_z - z p_y$ (cyclic permutation)
it makes sense to propose L_x eigenfunctions of the form

$$F_1^1 = -\sqrt{\frac{3}{8\pi}} \frac{y+iz}{r} \quad F_1^0 = \sqrt{\frac{3}{4\pi}} \frac{x}{r} \quad F_1^{-1} = \sqrt{\frac{3}{8\pi}} \frac{y-iz}{r}$$

Check:

$$L_x = \frac{\hbar}{i} \left[y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right]$$

$$L_x F_1^1 = -\frac{\hbar}{i} \sqrt{\frac{3}{8\pi}} \left\{ y \left[\frac{i}{r} + (y+iz) \frac{\partial}{\partial z} \left(\frac{1}{r} \right) \right] - z \left[\frac{1}{r} + (y+iz) \frac{\partial}{\partial y} \left(\frac{1}{r} \right) \right] \right\}$$

$$\frac{\partial}{\partial z} \left(\frac{1}{r} \right) = \frac{\partial}{\partial z} (x^2 + y^2 + z^2)^{-\frac{1}{2}} = \left(-\frac{1}{2} \right) (x^2 + y^2 + z^2)^{-\frac{3}{2}} \cdot (2z) = -\frac{z}{r^3}$$

Similarly

$$\frac{\partial}{\partial x} \left(\frac{1}{r} \right) = -\frac{x}{r^3} \quad \text{and} \quad \frac{\partial}{\partial y} \left(\frac{1}{r} \right) = -\frac{y}{r^3}$$

So

$$\begin{aligned}
 L_x F_1^1 &= -\frac{\hbar}{i} \sqrt{\frac{3}{8\pi}} \left\{ \frac{iy}{r} - \frac{z}{r} + (y+iz) \left[y \left(-\frac{z}{r^3} \right) - z \left(-\frac{y}{r^3} \right) \right] \right\} \\
 &= -\sqrt{\frac{3}{8\pi}} \hbar \left\{ \frac{y}{r} - \frac{z}{ir} \right\} = -\sqrt{\frac{3}{8\pi}} \hbar \left\{ \frac{y+iz}{r} \right\} = \hbar F_1^1 \quad \checkmark
 \end{aligned}$$

Next

$$\begin{aligned}
 L_x F_1^0 &= \frac{\hbar}{i} [y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y}] \sqrt{\frac{3}{8\pi}} \left(\frac{x}{r} \right) \\
 &= \frac{\hbar}{i} \sqrt{\frac{3}{8\pi}} \left\{ yx \frac{\partial}{\partial z} \left(\frac{1}{r} \right) - zx \frac{\partial}{\partial y} \left(\frac{1}{r} \right) \right\} \\
 &= \frac{\hbar}{i} \sqrt{\frac{3}{8\pi}} \left\{ yx \left(-\frac{z}{r^3} \right) - zx \left(-\frac{y}{r^3} \right) \right\} = 0 \quad \checkmark
 \end{aligned}$$

$$\begin{aligned}
 L_x F_1^{-1} &= \frac{\hbar}{i} \sqrt{\frac{3}{8\pi}} [y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y}] \frac{y-iz}{r} \\
 &= \frac{\hbar}{i} \sqrt{\frac{3}{8\pi}} \left\{ y \left(-\frac{i}{r} \right) - z \left(\frac{1}{r} \right) + (y-iz) \left[y \left(-\frac{z}{r^3} \right) - z \left(-\frac{y}{r^3} \right) \right] \right\} \\
 &= \hbar \sqrt{\frac{3}{8\pi}} \left\{ -\frac{y}{r} - \frac{z}{ir} \right\} = \hbar \sqrt{\frac{3}{8\pi}} \left(-\frac{y+iz}{r} \right) = -\hbar F_1^{-1} \quad \checkmark
 \end{aligned}$$

(b) If $L_z = \hbar$ and $L^2 = 2\hbar^2$ then the electron's wave function is

$$\psi = Y_1^1 = -\sqrt{\frac{3}{8\pi}} \frac{x+iy}{r}$$

To answer the question we need to write ψ as an expansion over L_x eigenfunctions.

Notice that

$$F_1^1 - F_1^{-1} = -\sqrt{\frac{3}{8\pi}} \frac{2y}{r}$$

\Rightarrow

$$\frac{i}{2} (F_1^1 - F_1^{-1}) = -\sqrt{\frac{3}{8\pi}} \frac{iy}{r}$$

$$-\sqrt{\frac{3}{8\pi}} \frac{x}{r} = -\frac{1}{\sqrt{2}} F_1^0$$

so by inspection

$$Y_1^1 = \frac{i}{2} F_1^1 - \frac{1}{\sqrt{2}} F_1^0 - \frac{i}{2} F_1^{-1}$$

The squares of the expansion coefficients give the probabilities

$$\begin{aligned} P(L_x = \hbar) &= \left| \frac{i}{2} \right|^2 = \frac{1}{4} \\ P(L_x = 0) &= \left| -\frac{1}{\sqrt{2}} \right|^2 = \frac{1}{2} \\ P(L_x = -\hbar) &= \left| -\frac{i}{2} \right|^2 = \frac{1}{4} \end{aligned}$$

(b) In general we have

$$\langle r \rangle = \langle \psi | r | \psi \rangle = \int_0^{\infty} R_{nl}^*(r) r R_{nl}(r) r^2 dr$$

2s: $R = 2 \left(\frac{1}{2a_0} \right)^{3/2} \left(1 - \frac{r}{2a_0} \right) e^{-r/2a_0}$

\Rightarrow

$$\langle r \rangle = 4 \left(\frac{1}{2a_0} \right)^3 \int_0^{\infty} \left(1 - \frac{r}{2a_0} \right)^2 r e^{-r/a_0} r^2 dr$$

Let

$$x = \frac{r}{a_0} \quad r = a_0 x \quad dr = a_0 dx \Rightarrow$$

$$\langle r \rangle = 4 \left(\frac{1}{2a_0} \right)^3 a_0^4 \int_0^{\infty} \left(1 - \frac{x}{2} \right)^2 x^3 e^{-x} dx$$

$$= \frac{a_0}{2} \int_0^{\infty} \left(x^3 - x^4 + \frac{x^5}{4} \right) e^{-x} dx$$

$$= \frac{a_0}{2} \left\{ 3! - 4! + \frac{5!}{4} \right\} = \frac{a_0}{2} \{ 6 - 24 + 30 \} = \boxed{6a_0}$$

Now 2p:

$$R(r) = \frac{1}{\sqrt{3}} \left(\frac{1}{2a_0} \right)^{3/2} \frac{r}{a_0} e^{-r/2a_0}$$

\Rightarrow

$$\langle r \rangle = \frac{1}{3} \left(\frac{1}{2a_0} \right)^3 \int_0^{\infty} \left(\frac{r}{a_0} \right)^2 e^{-r/a_0} r^3 dr$$

$$= \frac{1}{3} \left(\frac{1}{2a_0} \right)^3 a_0^4 \int_0^{\infty} x^2 e^{-x} x^3 dx$$

$$\langle r \rangle = \frac{1}{3} \left(\frac{1}{2}\right)^3 a_0 \cdot 5! = \boxed{5a_0}$$

62) (a) $V = -\frac{e^2}{4\pi\epsilon_0} \cdot \frac{1}{r}$ $R_{10}(r) = 2\left(\frac{1}{a_0}\right)^{3/2} e^{-r/a_0}$

so

$$\begin{aligned} \langle V \rangle &= -\frac{e^2}{4\pi\epsilon_0} \langle \frac{1}{r} \rangle = -\frac{e^2}{4\pi\epsilon_0} \int_0^{\infty} R_{10}^*(r) \frac{1}{r} R_{10}(r) r^2 dr \\ &= -\frac{e^2}{4\pi\epsilon_0} (4) \frac{1}{a_0^3} \int_0^{\infty} e^{-2r/a_0} r dr. \end{aligned}$$

Let

$$x = 2r/a_0 \quad r = \frac{a_0}{2} x \quad dr = \frac{a_0}{2} dx$$

$$\begin{aligned} \langle V \rangle &= -\frac{e^2}{4\pi\epsilon_0} (4) \frac{1}{a_0^3} \left(\frac{a_0}{2}\right)^2 \int_0^{\infty} x e^{-x} dx \\ &= -\frac{e^2}{4\pi\epsilon_0} \frac{1}{a_0} \times 1! \end{aligned} \quad a_0 = \frac{4\pi\epsilon_0 \hbar^2}{e^2 m}$$

so

$$\boxed{\langle V \rangle = -\left(\frac{e^2}{4\pi\epsilon_0}\right)^2 \frac{m}{\hbar^2} = -\left(1.44 \text{ eV}\cdot\text{nm}\right)^2 \frac{5.11 \times 10^5 \text{ eV}}{(197.3 \text{ eV}\cdot\text{nm})^2} = -27.2 \text{ eV}}$$

(b) $\langle T \rangle + \langle V \rangle = E = -\frac{1}{2} \left(\frac{e^2}{4\pi\epsilon_0}\right)^2 \frac{m}{\hbar^2}$

so

$$\boxed{\langle V \rangle = -\langle V \rangle + E = +\frac{1}{2} \left(\frac{e^2}{4\pi\epsilon_0}\right)^2 \frac{m}{\hbar^2} = +13.6 \text{ eV}}$$